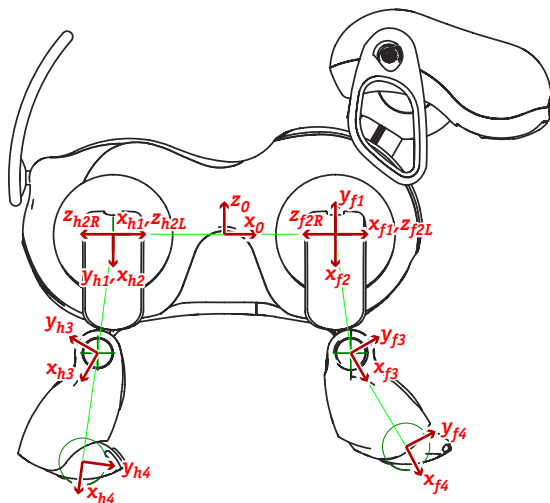
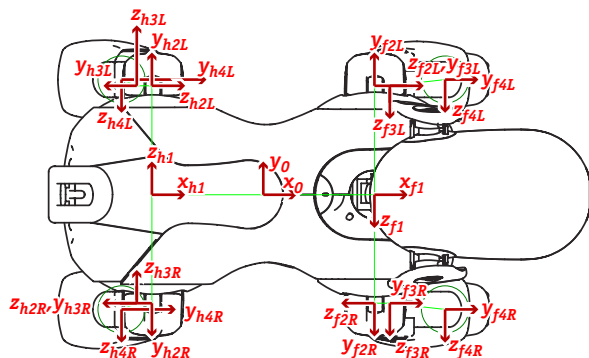


ERS-7 Legs



<input type="checkbox"/>	<input type="checkbox"/>	Δx	Δy	Δz
<input type="checkbox"/>	1. - shoulder	65	0	0
<input type="checkbox"/>	2. - elevator	0	0	62.5
<input type="checkbox"/>	3. - knee	69.5	0	9
<input type="checkbox"/>	f4. - ball	69.987	-4.993	4.7
<input type="checkbox"/>	h4. - ball	67.681	-18.503	4.7
<input type="checkbox"/>	Diameter of ball of foot is 23.433mm			
<input type="checkbox"/>	Each link offset is relative to previous link			

The shins shown in this diagram appear to be slightly distorted compared to a real robot. Corresponding measurements have been taken from actual models.

