

ERS-2xx Legs

	Δx	Δy	Δz
□ 1. - shoulder	59.5	0	0
□ 2. - elevator	0	0	59.2
□ 3. - knee	64	0	12.8
□ f4. - ball	55.748	-11.708	0.5
□ h4. - ball	60.627	-22.171	0.5

Paw button is intersection of a 24.606 diameter
 □ cylinder and a 27.922 diameter sphere

Each link offset is relative to previous link
 Legs are shown with knees bent at 35°

